Important: This document should be read carefully before commencing installation
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Dear 4B Customer:

Congratulations on your purchase. 4B appreciates your business and is pleased you have chosen our products to meet your needs.

Please read in its entirety and understand the literature accompanying the product before you place the product into service. Please read the safety precautions carefully before operating the product. With each product you purchase from 4B, there are some basic but important safety considerations you must follow to be sure your purchase is permitted to perform its design function and operate properly and safely, giving you many years of reliable service. Please read and understand the Customer Safety Responsibilities listed below. Failure to follow this safety directive and the Operation Manuals and other material furnished or referenced, may result in serious injury or death.

SAFETY NOTICE TO OUR CUSTOMERS

A. In order to maximize efficiency and safety, selecting the right equipment for each operation is vital. The proper installation of the equipment, and regular maintenance and inspection is equally important in continuing the proper operation and safety of the product. The proper installation and maintenance of all our products is the responsibility of the user unless you have asked 4B to perform these tasks.

B. All installation and wiring must be in accordance with Local and National Electrical Codes and other standards applicable to your industry. (Please see the article “Hazard Monitoring Equipment Selection, Installation and Maintenance” at www.go4b.com.) The installation of the wiring should be undertaken by an experienced and qualified professional electrician. Failure to correctly wire any product and/or machinery can result in the product or machine failing to operate as intended, and can defeat its design function.

C. Periodic inspection by a qualified person will help assure your 4B product is performing properly. 4B recommends a documented inspection at least annually and more frequently under high use conditions.

D. Please see the last page of this manual for all warranty information regarding this product.

CUSTOMER SAFETY RESPONSIBILITIES

1. READ ALL LITERATURE PROVIDED WITH YOUR PRODUCT

Please read all user, instruction and safety manuals to ensure that you understand your product operation and are able to safely and effectively use this product.

2. YOU BEST UNDERSTAND YOUR NEEDS

Every customer and operation is unique, and only you best know the specific needs and capabilities of your operation. Please call the 24-hour hotline at 309-698-5611 for assistance with any questions about the performance of products purchased from 4B. 4B is happy to discuss product performance with you at any time.
3. SELECT A QUALIFIED AND COMPETENT INSTALLER

Correct installation of the product is important for safety and performance. If you have not asked 4B to perform the installation of the unit on your behalf, it is critical for the safety of your operation and those who may perform work on your operation that you select a qualified and competent electrical installer to undertake the installation. The product must be installed properly to perform its designed functions. The installer should be qualified, trained, and competent to perform the installation in accordance with Local and National Electrical Codes, all relevant OSHA Regulations, as well as any of your own standards and preventive maintenance requirements, and other product installation information supplied with the product. You should be prepared to provide the installer with all necessary installation information to assist in the installation.

4. ESTABLISH AND FOLLOW A REGULAR MAINTENANCE AND INSPECTION SCHEDULE FOR YOUR 4B PRODUCTS

You should develop a proper maintenance and inspection program to confirm that your system is in good working order at all times. You will be in the best position to determine the appropriate frequency for inspection. Many different factors known to the user will assist you in deciding the frequency of inspection. These factors may include but are not limited to weather conditions; construction work at the facility; hours of operation; animal or insect infestation; and the real-world experience of knowing how your employees perform their jobs. The personnel or person you select to install, operate, maintain, inspect or perform any work whatsoever, should be trained and qualified to perform these important functions. Complete and accurate records of the maintenance and inspection process should be created and retained by you at all times.

5. RETAIN AND REFER TO THE OPERATION MANUAL FOR 4B’S SUGGESTED MAINTENANCE AND INSPECTION RECOMMENDATIONS

As all operations are different, please understand that your specific operation may require additional adjustments in the maintenance and inspection process essential to permit the monitoring device to perform its intended function. Retain the Operation Manual and other important maintenance and service documents provided by 4B and have them readily available for people servicing your 4B equipment. Should you have any questions, please call the 4B location who supplied the product or the 24-hour hotline number in the USA -309-698-5611.

6. SERVICE REQUEST AND ONLINE PRODUCT REGISTRATION

If you have questions or comments about the operation of your unit or require the unit to be serviced please contact the 4B location who supplied the product or send your request via fax (309-698-5615), email (4b-usa@go4b.com), or call us via our 24-hour hotline number in the USA - 309-698-5611. Please have available product part numbers, serial numbers, and approximate date of installation. In order to assist you, after the product has been placed into service, complete the Online Product Registration section which is accessed via our website www.go4b.com
Approvals

Certification Markings: Model B4004V4C/B4004V46C
CSA Class II, Div. 2 - Groups F, G T125°C (A4004V46C)
Ex tc IIIc T125°C Dc IP66 Tamb -20°C to +45°C
Zone 22 AEx tc IIIc T125°C Dc IP66 Tamb -20°C to +45°C

CSA Class II, Div. 1 - Groups E, F, G T125°C (A4004V4C)
(R5004V4C - When Powered with a Class 2 Power Supply)
Ex tb IIIc T125°C Db IP66 Tamb -20°C to +50°C
Zone 21 AEx tb IIIc T125°C Db IP66 Tamb -20°C to +50°C

Power dissipation in Watts
CSA Division 1 : 12 Watts
CSA Division 2 : 12 Watts

To Open the Lid:
1. Disconnect power (isolate ALL circuits)
2. Untighten the lid securing screws
3. Carefully open the lid ensuring that the gasket is not damaged and remains in place

To Close the Lid:
1. Check that the gasket is correctly fitted into the box groove and is undamaged.
2. Tighten the lid screws.
3. Check that the lid and box are correctly mated.

Special conditions for safe use:
WARNING: Static Hazard - Clean only with a damp cloth.
B400 ELITE BELT ALIGNMENT MONITOR

INTRODUCTION

The B400 Elite is a microprocessor controlled unit which is able to accept signals of alignment from one or two belt conveyors and is able to cause alarm and shutdown of the conveyor and or feeders, when hazardous conditions are detected. The control unit is housed in a self contained wall-mounting enclosure, and the alignment sensors are separate items for mounting on the conveyor. The B4004V46 Elite will operate from 100 to 240v AC ±10% or 24v DC ±10%.

The belt alignment sensors operate in pairs to detect the correct alignment of belts used on conveyors, elevators and other similar equipment. The control unit can accept signals from pairs of sensors which may be on one or on two separate belts. When both pairs of sensors are mounted on one conveyor, they are intended to monitor each end of the belt. When both pairs of sensors are mounted on two different conveyors, they are intended to monitor the units independently.

1. SPECIFICATIONS

1.1 The Control Unit

A plastic enclosure houses the electronics and terminal connectors. The unit contains a printed circuit board to accommodate power supply circuitry, output relays, microprocessor and terminals. A short ribbon cable is connected to the lid of the enclosure where the indicator lamps are mounted. Adjustments are provided on the printed circuit board for setting up. A ‘touch button’ is mounted in the lid to allow the unit to be tested during operation.

Electrical Supply (B4004V46C) - 100 to 240 VAC ±10% 50/60Hz
                        - 24 VDC ±10%
Electrical Supply (B4004V4C) - 24 VDC ±10%
Power Consumption - 12 WATTS (Max)
Alarm Relay A Contacts - 1 Pole normally open 8A@ 250VAC Non Inductive
Alarm Relay B Contacts - 1 Pole normally open 8A@ 250VAC Non Inductive
Stop Relay A Contacts - 1 Pole normally open 8A@ 250VAC Non Inductive
Stop Relay B Contacts - 1 Pole normally open 8A@ 250VAC Non Inductive
Sensor Inputs - 10 to 30 VDC (Or same as supply)
Sensor Supply - See Note 1: Current 200 ma available per sensor
Terminals - Power 2.5mm² 16 AWG max
                        - Signals 2.5mm² 16 AWG max Plug In
Protection - Class II, Division 1, Groups E, F & G (V4)
When powered with a class2 power supply.
Tamb -20°C to +50°C IP66
Class II, Division 2, Groups F & G (V46)
Tamb -20°C to +45°C IP66
<table>
<thead>
<tr>
<th>Specification</th>
<th>Details</th>
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<tr>
<td>Height</td>
<td>9.7”, 246mm</td>
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<tr>
<td>Width</td>
<td>7.4”, 188mm</td>
</tr>
<tr>
<td>Depth</td>
<td>4”, 102mm</td>
</tr>
<tr>
<td>Fixing Centres</td>
<td>8.75” high x 4” wide, 223mm x 102mm</td>
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<tr>
<td>Cable Entry</td>
<td>2 Holes 1⅛” DIA, 27.5mm, ¾” CONDUIT</td>
</tr>
<tr>
<td>Weight</td>
<td>3lbs, 1.3Kg</td>
</tr>
<tr>
<td>Status Indicator Lamps</td>
<td>Viewed through front panel</td>
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<tr>
<td></td>
<td>POWER</td>
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<tr>
<td></td>
<td>SENSOR 1A</td>
</tr>
<tr>
<td></td>
<td>SENSOR 2A</td>
</tr>
<tr>
<td></td>
<td>MISALIGNMENT A</td>
</tr>
<tr>
<td></td>
<td>SENSOR 1B</td>
</tr>
<tr>
<td></td>
<td>SENSOR 2B</td>
</tr>
<tr>
<td></td>
<td>MISALIGNMENT B</td>
</tr>
<tr>
<td></td>
<td>ALARM</td>
</tr>
<tr>
<td></td>
<td>STOP A</td>
</tr>
<tr>
<td></td>
<td>STOP B</td>
</tr>
<tr>
<td>Touch Button</td>
<td>TEST</td>
</tr>
</tbody>
</table>

**Internal adjustments**

- Alarm Delay Low/High Sensor Inputs A
- Alarm Delay Low/High Sensor Inputs B
- Stop Delay Low/High Sensor Inputs A
- Stop Delay Low/High Sensor Inputs B
- Belt misalignment when signal Low/High A
- Belt misalignment when signal Low/High B

1.2 The Belt Alignment Sensors

The B400 Elite has been optimised to work with
TouchSwitch type TS2V4C (24 VDC only)
Capacitance sensor BS15V10A (24 VDC 5 wire)
The above sensors are certified Class II Division1 Groups E,F&G

You may use any device which has a voltage free contact available such as a relay, a micro switch or other mechanically operated switch. The B400 inputs are rated at 30 VDC at 20ma maximum.

Other sensors may also be used but the application may vary from the examples given in this manual. Please contact your supplier if you wish to consider other alternative sensor types. The **maximum** power available to sensors is 200ma per sensor (see page 9).
2 INSTALLATION INSTRUCTIONS
Warning: Always lock-out and tag-out the machine prior to installation and set-up.

Wiring: All Wiring Must Be In Accordance With Local and National Electrical Codes and Should Be Undertaken By an Experienced and Professional, Qualified Electrician.

2.1 The Control Unit

The Control Unit box should be installed in a suitable control or starter switch room and mounted at an eye level position so that the warning lights can be readily seen. The box should have sufficient space to open the lid for wiring and adjustment. An audible alarm, sounder or visual indicator lamp can be installed in or outside of the control room.

ATTENTION
The Control Unit is susceptible to static voltage. Connection of a clean ground to terminal 31 is essential for optimum performance. Prior to this connection, static handling precautions should be taken.

Enclosure Installation:
a. The IP66 rating of the enclosure must be maintained when used in Zone 20 and 21 dust environment. You must use the correct cable, glands and sealing arrangement and in accordance with the installation codes detailed in local national regulations.
b. Where other certified components are used as part of the assembly or installation procedure, the user must take in to account any limitations which might be listed on the relevant certificates.
c. The box is supplied with 2 x 27.5mm (1⅛”) pre drilled holes in the bottom face. Unused entry apertures must be sealed using component certified stopping plugs Hawke International type 375 or 387. The end user must install component or apparatus certified stopping plugs and cable glands in strict accordance with the manufacturer’s instructions. Further holes must not be added to the enclosure as this will invalidate any warranty and the product certification.
d. All wiring must be carried out in accordance with relevant codes of practice and / or instructions.
e. The voltage and current and maximum power dissipation shown on the box label must not be exceeded.
f. The wiring insulation must extend to within 1 mm of the metal face of the terminal.
g. All leads must be insulated for the appropriate voltage.
h. Not more than 1 single or multiple strand cable is to be connected to any terminal unless multiple conductors have previously been joined in a suitable manner (e.g. boot lace ferrule) such that they present a single connection point to the terminal.
i. A parallel shaft screwdriver of the correct size should always be used when tightening terminals.
2.2 The Alignment Sensors

Two alignment sensors are required to be mounted on each conveyor/elevator. See page 6 for recommended types.

3 ELECTRICAL WIRING

Refer to Drawings D to J

Terminal (Shield) is used to provide a continuous shield connection for the communications cable and is not grounded in the B400

Terminal 1 and 2 (A+ and B-) are used for the RS485 serial communications bus (HotBus). Care should be taken to ensure that the connections are observed. Incorrect connection can result in loss of communications between nodes.

**WARNING:** under no circumstances must the power supply connection be allowed to come into contact with these terminals; to do so would result in the failure of the communications interface.

Terminals 3 and 4 (+ and 0V) are used to provide a 24 DC supply to the HotBus network node when required. This supply can be disabled by switch SW2 and is protected by F5.

Terminal 5 is used to provide +24 VDC power to sensor 1A and is protected by F1
Terminal 6 is used as input signal for channel 1A
Terminal 7 is not connected
Terminal 8 is 0 VDC for sensor 1A

Terminal 9 is used to provide +24 VDC power to sensor 2A and is protected by F2
Terminal 10 is used as input signal for channel 2A
Terminal 11 is not connected
Terminal 12 is 0 VDC for sensor 2A

Terminal 13 is used to provide +24 VDC power to sensor 1B and is protected by F3
Terminal 14 is used as input signal for channel 1B
Terminal 15 is not connected
Terminal 16 is 0 VDC for sensor 1B

Terminal 17 is used to provide +24 VDC power to sensor 2B and is protected by F4
Terminal 18 is used as input signal for channel 2B
Terminal 19 is not connected
Terminal 20 is 0 VDC for sensor 2B

Terminals 21 and 22 are volt free Alarm contacts for Alarm relay B rated 250 VAC @ 8 Amp non inductive.
Terminals 23 and 24 are volt free Alarm contacts for Alarm relay A rated 250 VAC @ 8 Amp non inductive.

Terminals 25 and 26 are volt free Stop contacts for Stop relay B rated 250 VAC @ 8 Amp non inductive.
Terminals 27 and 28 are volt free Stop contacts for Stop relay A rated 250 VAC @ 8 Amp non inductive.

Terminals 29 and 30 are for the AC power supply. This is only fitted when the B4004V46C is to be used in a Zone 22 application. The AC supply can be between 100 and 240 Volts ± 10% 50/60 HZ.

Terminal 31 is used for a ground (earth) -ve terminal when using a mains power supply or a 0 VDC terminal when using a separate DC power supply.

Terminal 32 is used for a positive +ve terminal when powering the B400 from a separate 24 VDC power supply.

**Fuses:**

It is very important to observe the fuse ratings used on the B400 elite. The following fuse ratings MUST apply. See page 3 for the position of the fuses. Fuses 1 to 4 are located on the underside of the plug in circuit board to provide mechanical protection.

F1 to F5 must have a maximum rating of 200ma when used in a Zone 21 installation.
F1 to F4 has a recommended maximum rating of 200ma when used in a Zone 22 installation. F5 can be 2 amp maximum.

F1 to F4 are used to limit the current available to each of the 4 sensors.
F5 is used to limit the current available to the internal electronics and terminals 3 and 4.

F6 is used to protect the AC power supply and should have a 2 Amp rating. This fuse is only required when used in Zone 22 installations.

In order to maintain the product certification, these fuses MUST be replaced with equivalent fuses at the same rating. Failure to do so will invalidate the certification and any warranties which may exist.

## 4 OPERATING INSTRUCTIONS

### 4.1 Adjustment of Alignment Sensors

Note: If the control unit is mounted in a hazardous area, switch the electrical supply **OFF before** opening the lid of the control unit to make the following adjustments. Close the lid **before** switching the electrical supply **ON**. Repeat this each time an adjustment is required inside the control unit.

Ensure that the Alignment Sensors have been correctly mounted as described in paragraph 2.2. At this point it will be necessary to start the belt. Note that until the sensors are correctly set up and adjusted, the belt may not run continuously subject to the
method of wiring to the motor starter. With the belt running and correctly aligned, adjust
the sensitivity control potentiometers on each sensor in order to ensure a stable signal that
is not affected by things such as vibration or loose material. When all sensor adjustments
are complete, test the complete assembly to ensure that both sensors operate as expected.

4.2 Adjustment of Switches

When used in a Zone 21 installation, ensure that the electrical supply to the control
unit is OFF before opening the control unit lid.

Open the lid of the control unit and locate 8 small slide switches, near the left hand row
of terminals. Initially all 8 switches should be in the left position.

SWITCH 1 (Top) sets the delay between detecting a misalignment condition for sensors
1A and 2A, and energising ALARM RELAY ‘A’. Left = 5secs, Right = 30secs

SWITCH 2 Sets the delay between detecting a misalignment condition for sensors 1B and
2B, and energising ALARM RELAY ‘B’. Left = 5secs, Right = 30secs

SWITCH 3 Sets the delay between energising ALARM RELAY ‘A’ and de-energising
STOP RELAY ‘A’. Left = 30secs, Right = 60secs.

SWITCH 4 Sets the delay between energising ALARM RELAY ‘B’ and de-energising
STOP RELAY ‘B’. Left = 30secs, Right = 60secs.

SWITCH 5 Sets the normal operating level for the sensors 1A and 2A. Set to the left
(HIGH) position expects the signal from the sensor to be normally high and to go low
when a misalignment is detected. Set to the right (LOW) position expects the signal from
the sensor to be normally low and to go high when a misalignment is detected.

SWITCH 6 Sets the normal operating level for the sensors 1B and 2B. Set to the left
(HIGH) position expects the signal from the sensor to be normally high and to go low
when a misalignment is detected. Set to the right (LOW) position expects the signal from
the sensor to be normally low and to go high when a misalignment is detected.

It is recommended that the B400 should be used with switch 5 and 6 set to the high
position and with the appropriate sensor connections as this provides ‘fail safe’ detection.
In this mode, should the wiring become cut or if a sensor was to fail, then the B400
would see this as a misalignment and stop the conveyor/elevator which is a safe position
in which to fail.

SWITCH 7 & 8 are not used.
4.3 The TEST function

4.3.1 Normal Test

The B400 Elite is equipped with a self test function, initiated by the test touch button on the lid of the control unit. When the button is touched the Alarm lamp flashes and then the following automatic test is initiated as the button is released.

1. All lamps illuminate – the ALARM lamp continues to flash
2. After 5 seconds all lamps return to their normal conditions

This test can be performed when the elevator is running or stopped and tests the correct function of the microprocessor and of all lamps.

4.3.2 Extended Test

If the Normal Test is initiated as in 4.3.1 and if the test touch button is touched again, while the ALARM lamp is flashing, the extended test operates as follows:

1. All lamps illuminate – the ALARM lamp continues to flash
2. Touching the test sensor again
3. The ALARM and STOP A lamps flash for a further 5 seconds (8 seconds total time)
4. The ALARM RELAY and STOP RELAYS are inverted and the ALARM, STOP A and STOP B lamps flash
5. After 3 seconds all lamps and relays return to their normal conditions

If this test is performed when the elevator is not running, the Alarm will sound but the STOP RELAYS will have no effect on the conveyor/elevator. If this test is performed when the conveyor/elevator is running, the Alarm will sound and the STOP RELAYS will stop the conveyor. If this test is performed when the B400 has stopped a conveyor, the relevant stop relay will re-energise during the test. This test should be performed on a regular basis to check the safety of the installation.

The touch button has been designed to ignore the first 0.5 seconds of touch; this is to reduce the possibility of accidental activation. Once activated as indicated by the led adjacent to the touch pad, removing the finger deactivates the button, if you leave your finger in place, the touch button will only remain active for approximately 2 seconds before automatically de-activating again. The touch button continuously recalibrates in order to eliminate the effects of static, dust or moisture build up on the surface.

4.4 Power up state

The B400 Elite conducts a self test at power up. After the self test is complete stop relays A and B will both energise, allowing the conveyor(s) to be started. If a belt or sensor is misaligned at this point, then the misalignment cycle will begin. On completion of the cycle, the stop relay associated with the sensor will de-energise and not allow starting of the conveyor or it will stop the conveyor if already started.
4.5 Normal Running

As long as the relevant sensors both detect correctly, the belt is considered to be running normally and the relevant STOP relay will remain energised and the STOP indicator lamps will remain off.

4.6 Normal Stopping

The conveyor may be stopped at any time in the usual manner. The B400 will not interfere with this process unless you have wired the stop relays in series with the conveyor motor contactor circuits and a belt misalignment has been detected.

4.7 Misalignment Alarm

If one of the sensors detects a belt misalignment and this misalignment persists for more than 2 seconds, the amber belt misalignment led will illuminate. After a 5 or 20 seconds (set by either switch 1 or switch 2) the red alarm led will be illuminated and the relevant alarm relay will energise. If the belt becomes realigned again during this period, the misalignment led, alarm led and alarm relay will automatically be reset.

4.8 Misalignment Stop (Shutdown)

If the alarm relay remains energised for a time which is longer than 30 or 60 seconds (set on switch 3 or 4), the relevant STOP RELAY will de-energise and the relevant STOP lamp will energise. If the B400 is wired to operate with two independent conveyers, then only the conveyor with the misaligned belt will be stopped.

4.9 Restarting

If the conveyor has been stopped due to a belt misalignment alarm, you must first correct the belt misalignment before attempting to restart the conveyor. Failure to correct the problem will result in the B400 preventing the restart of the conveyor because the stop relay will be de-energised.

4.10 Two Separate Conveyors

If the A1+A2 and B1+B2 sensors are fitted to two separate conveyors, the above descriptions 4.1 to 4.9 apply separately to each belt and separate ALARM and STOP relays can be used.

4.11 One Conveyor with Four Sensors

If the A1+A2 and B1+B2 sensors are mounted on the same conveyor/elevator, (for example A1+A2 at the far end and B1+B2 at the near end) the control unit will differentiate between misalignment faults at the two sensor locations. Normally, the two STOP relays would be connected so that either/both can stop the conveyor and either/both alarm relay will operate the alarm indicator.
4.12 Liability and Indemnity:

1) In respect of installation or applications of the goods as parts or components of other goods or machinery the buyer shall be solely responsible for the compliance and the installation with safety regulations issued by competent authorities and in force at the place of operation and/or for its compliance with any terms of insurance notified by the Buyer’s insurance for personal injury or damage to property or loss of profit though fire, explosion, gas, or otherwise.

2) Neither the company nor its suppliers shall in any circumstances whatsoever be liable for any loss or damage suffered by the Buyer or by any third party howsoever caused involving any person, property, or interest, suffered by the Buyer or any third party directly or indirectly in connection with the use, functioning or state of the goods, unless the same shall arise out of the Company’s negligence.

3) The buyer shall indemnify the Company against all actions, claims, or demands by third parties, whether in tort or otherwise, howsoever arising, directly or indirectly, in connection with the use, functioning or state of the goods or in connection with the performance of service.

Limitation of Liability

Without prejudice to the foregoing, the Company shall in no circumstances be liable:

1) For any incidental or consequential loss or damage suffer by the buyer, including without limitation, delay, detention, loss of production, loss of profit, or liability to third parties except liability for personal injury or death arising out of negligence by the Company.

2) For any loss or damage covered by the insurance or which would ordinarily be covered by the insurance.

Warranty

The equipment is covered by 12 months warranty from the date of dispatch. Any faults arising due to faulty materials or workmanship in the original equipment within the warranty period will be corrected free of charge providing the equipment is returned to us freight paid.
Contact Information.

go4b.com
CHECKLIST

For problems after initial start-up

1. Is there excessive interference on the electrical power supply? Power conditioners and surge (spike) suppressor may have to be fitted.

2. Has the wiring for the Sensors been routed away from power cables? See paragraph 2.2.

3. Are the Sensors mounted away from plastic abrasion liners (which could cause static interference), electric motors and other magnetic fields?

4. Is the B400 Elite circuit properly grounded?

5. Is the conveyor/elevator grounded to prevent static build-up?

6. Is the belt running true?

7. Does the belt stay in alignment when material is fed onto it?

8. Is the conveyor/elevator belt tightened up sufficiently to prevent belt slip and misalignment?

9. Have the Sensors been mounted rigidly and free from vibration?

10. Check that the Sensors do not foul the equipment.

11. Is the Micro-processor control unit overheating, if so mount in a temperature-controlled environment of maximum temperature 104°F (40°C).

12. Check that high powered ‘Walkie Talkie’ radios are not operated immediately near the B400 Elite control unit or Sensors as this will affect the performance.

13. If your conveyor/elevator has a weighted take up please ensure that there is sufficient weight on it to prevent belt slip.
<table>
<thead>
<tr>
<th>SYMPTOM</th>
<th>CAUSE</th>
<th>REMEDIAL ACTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>LED on Alignment Sensor flashes</td>
<td>The sensitivity is incorrectly adjusted.</td>
<td>Adjust the sensitivity until the signal is stable</td>
</tr>
<tr>
<td></td>
<td>Wiring connection faulty</td>
<td>Check wiring</td>
</tr>
<tr>
<td>LED on Alignment Sensor does not change state</td>
<td>Sensor adjustment incorrect</td>
<td>Sensitivity adjustment to high</td>
</tr>
<tr>
<td></td>
<td>Interference in wiring</td>
<td>Use shielded cable and rigid conduit</td>
</tr>
<tr>
<td>Sensor LED on Control unit does not change when the belt is misaligned</td>
<td>Sensor position wrong</td>
<td>See section 1 above</td>
</tr>
<tr>
<td></td>
<td>Sensor not operating</td>
<td>Check wiring</td>
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<tr>
<td></td>
<td>Wiring Fault</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Sensor connected to wrong terminals</td>
<td></td>
</tr>
<tr>
<td>Wrong Sensor LED on unit lights</td>
<td>Sensor connected to wrong input</td>
<td>See drawings H to J</td>
</tr>
<tr>
<td>Alarm LED on</td>
<td>Belt misaligned</td>
<td>Check belt</td>
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<tr>
<td>Stop LED on</td>
<td>Stop condition occurred</td>
<td>Check belt</td>
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<tr>
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<td>Belt misaligned</td>
<td>Check sensors</td>
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<tr>
<td>Belt fails to start</td>
<td>Belt alignment incorrect</td>
<td>Check belt</td>
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<td>Sensor alignment incorrect</td>
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<td>Wiring fault</td>
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</tr>
<tr>
<td>Belt starts but fails to keep running</td>
<td>Belt alignment incorrect</td>
<td>Check belt</td>
</tr>
<tr>
<td></td>
<td>Sensor alignment incorrect</td>
<td>Check sensor alignment</td>
</tr>
<tr>
<td></td>
<td>Wiring fault</td>
<td>Check wiring</td>
</tr>
</tbody>
</table>
This drawing represents a general arrangement for the components used in a typical B400 installation. The following pages give more details about the mechanical and electrical requirements of the B400 and the sensors available for use with it.
Examples of sensor positioning for belt misalignment detection.

![Diagram of sensor positioning](image)

**Drawing ‘B’**

When using the BS15V10A sensor in this way it is recommended that you set switch 5 and/or 6 to the left (high) position in order to provide failsafe operation.
Refer to the wiring section (Drawings H to J) for connections details for the different sensors.
AC Supply connection details for the B400 Elite

**Drawing ‘D’**

**ONE ELEVATOR - AC SUPPLY WITH FOUR SENSORS (1A, 2A, 1B, 2B)**

**Drawing ‘E’**

**ONE ELEVATOR - AC SUPPLY WITH TWO SENSORS (1A AND 2A) ELEVATOR A**
DC Supply connection details for the B400 Elite

Drawing ‘F’

Drawing ‘G’
ALTERNATIVE SENSOR TYPES USED WITH THE B400 ELITE BELT ALIGNMENT MONITOR

CONNECTION DETAILS FOR THE BS15V10A SENSOR CONNECTED TO THE B400 ELITE

**SENSOR 1A**
- **BROWN**
- **BLACK**
- **BLUE**
  - 5 +24 VDC 1A
  - 6 INPUT 1A
  - 7 N/C
  - 8 0V

**SENSOR 1B**
- **BROWN**
- **BLACK**
- **BLUE**
  - 9 +24 VDC 2A
  - 10 INPUT 2A
  - 11 N/C
  - 12 0V

**SENSOR 2A**
- **BROWN**
- **BLACK**
- **BLUE**
  - 13 +24 VDC 1B
  - 14 INPUT 1B
  - 15 N/C
  - 16 0V

**SENSOR 2B**
- **BROWN**
- **BLACK**
- **BLUE**
  - 17 +24 VDC 2B
  - 18 INPUT 2B
  - 19 N/C
  - 20 0V

**NOTE 1:** WIRE BLACK/ORANGE OR BLACK/RED MAY BE USED TO CONNECT THE SENSOR TO THE B400. THE CHOICE IS DEPENDANT UPON WHICH RELAY CONTACT YOU INTEND TO USE.

Ensure that the unused wire is properly insulated against unintended connection.

When using the BS15V10A sensor in this way it is recommended that you set switch 5 and/or 6 to the left (high) position in order to provide failsafe operation.

Drawing ‘H’
When using the TouchSwitch in this way it is recommended that you set switch 5 and/or 6 to the left (high) position in order to provide failsafe operation.

Drawing ‘I’
GENERAL CONNECTION DETAILS FOR THREE WIRE CAPACITOR SENSORS CONNECTED TO THE B400 ELITE

NOTE 1: THE WIRING COLOURS USED WILL BE DETERMINED BY THE SENSOR USED. PLEASE REFER TO THE SENSOR MANUAL FOR DETAILS. THE B400 WILL WORK WITH NPN OR PNP OUTPUT TYPES DEPENDANT UPON THE SETTING OF SWITCH 5 AND 6 OF THE B400. WE RECOMMEND USING A TYPE THAT ALLOWS FOR FAIL SAFE OPERATION.

Drawing ‘J’
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